



RobustSENSE Final Event

16 May 2018 in Ulm, Germany



Final Event - Agenda 1

Time	TOPIC	WHO?
09:00 – 09:30	Registration and Coffee	
09:30 – 09:45	Opening	Georgi Kuzmanov, Programme Officer
09:45 – 10:30	The RobustSENSE Approach	Werner Ritter, Coordinator
10:30 – 11:00	Requirements and Architecture	Bernd Schäufele
11:00 – 11:30	The Sensor and Fusion Layer	Klaus Dietmayer
11:30 – 12:00	Situation Understanding and Planning Layer	Florian Kuhnt
12:00 – 12:30	Prototypes and Testing	Pablo Mejuto
12:30 – 12:45	Demonstration and Exhibition	Werner Ritter
12:45 – 13:30	LUNCH	

Final Event - Agenda 2

Time	TOPIC	WHO?
12:45 – 13:30	LUNCH	
13:30 – 17:30	<p>Project exhibition with access to new hardware, posters, video presentations, a live-stream from Berlin and an exploitation workshop.</p> <p>Driving demonstrations for:</p> <ul style="list-style-type: none">▼ Automatic road surface condition determination,▼ Stereoscopic environment perception,▼ Coping with noncompliant behaviours,▼ Autonomous driving adjustment by sensor performance degradation,▼ Pedestrian detection in foggy conditions,▼ Lane change assist and soil detection	
17:30	CLOSING & FAREWELL	